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Results Key:
JNL = Journal or Magazine **CNF** = Conference **STD** = Standard
1 Staying alive: a docking station for autonomous robot recharging
Silverman, M.C.; Nies, D.; Jung, B.; Sukhatme, G.S.;

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5 Accurate pose estimation from a single perspective view
Abidi, M.A.; Chandra, T.;

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8 Docking techniques and evaluation trials of the SWIMMER AUV: an autonomous deployment AUV for work-class ROVs

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10 Communication system of cellular robot: CEBOT

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